



# A Bayesian Network-Based Approach to Digital Mammography Lesion Classification

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## Article Info

Received: 17-02-2014

Revised: 02-03-2014

Accepted: 06-04-2014

Published: 17/05/2014

**Abstract :** Worldwide, breast cancer is a major concern for women. When cancer cells begin to grow in the breast, the resulting disease is known as breast cancer. Various screening methods are accessible for the purpose of detecting breast cancer. This publication presents many techniques for the detection of breast cancer. The first stage of this work was eliminating background noise from the images. To do this, the authors used a median filter. When searching the MIAS database, you may find images with pectoral muscles; to eliminate them, just calculate the image's thresholding value. We suggest using an entropy-based segmentation method to divide up a grayscale breast picture. This method determines the entropy value and histogram of a picture. The output displays the segmented picture after determining the image's thresholding value. An entropic technique for noisy cell picture segmentation is proposed in this research, and it is efficient and quick. Following the segmentation process, a variety of characteristics are extracted from the picture, including standard deviation, entropy, skewness, kurtosis, variance, energy, correlation, smoothness, and root mean square. These features are then fed into a Bayesian network, which uses them to categorize the image based on their values. In comparison to previous methods, the experimental findings demonstrate that the suggested approach is both efficient and noise-tolerant.

**Keywords:** Median filter, entropy, ROI, pectoral muscle, breast cancer, Bayesian network

## 1. Introduction

2. Among females across the globe, breast cancer is by far the most frequent kind of breast cancer. Cancers that originate in the breast cells are known as breast cancers. Worldwide, breast cancer accounts for over 18.2% of all cancer-related fatalities, regardless of gender. In industrialized countries, breast cancer is a much more significant problem than in less developed ones. Breast cancer is more frequent in older women for a number of reasons; one is that women in wealthy countries tend to live longer than those in poorer ones. One reason for this is that women in wealthy nations



tend to eat and live differently than women in disadvantaged ones. Annually, there are 232,380 cases of breast cancer in women and 2,240 cases in men in the United States, as reported by the National Cancer Institute. The World Health Organization (WHO) reports that seven lakh people in India lose their lives to cancer each year, with over ten lakh receiving a cancer diagnosis.

The origin of breast cancer is from the inner lining of milk ducts or the lobules that supply them with milk. Malignant tumor spread to other parts of the body. The breast cancer that starts off in the lobules is known as lobular carcinoma, while one that developed from the ducts is called ductal carcinoma. There are billions of microscopic cells available in the body. The cancer cells multiply in orderly fashion new cells are made to replace the ones that died.

The majority of breast cancer occurs in the females. The invasive breast cancer is spread over the body part such as bones, liver or lungs and the non-invasive breast cancer is still inside its place of origin and has not broken out. In cancer, the cells multiply uncontrollably and there are too many cells, progressively more and more than there should be. However, it is difficult for radiologists to provide accurate and uniform evaluation for the mammograms generated. The advances of digital image processing radiologist have an opportunity to improve their diagnosis with the aid of computer system. In this paper the median filter is used to remove noise in the image. Filtering is the technique for modifying or enhancing an image. After removing noise from the image the pectoral muscles are removed from the image. The entropy segmentation is used to detect ROI which is present in the image. The features are extracted from the ROI part of image and then given to the classifier to classify the image is normal or abnormal. The paper is organized as follows: Section 2 presents the flow of the method, preprocessing phase, segmentation, feature extraction and classifier. Section 3 shows the implementation and result.

### **3. Materials and Methods**

#### **3.1 Preprocessing**

The main goal of the preprocessing is to improve the image quality to make it ready to further processing by removing or reducing the unrelated and surplus parts in the background of the mammogram image. Mammograms are medical images that complicated to interpret. To remove the noise and unwanted data median filter is used. Median filter preserves edges while removing noise. Image processing operations implemented with filtering include smoothing,

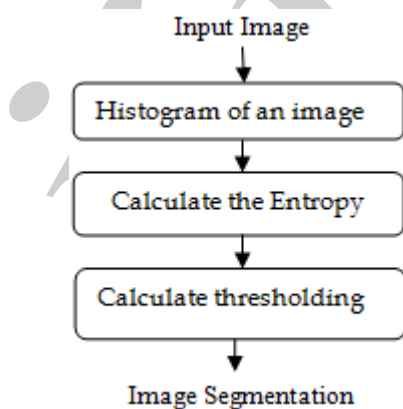


sharpening, and edge enhancement. In image processing filters are mainly used to suppress either the high frequencies in the image, *i.e.* smoothing the image, or the low frequencies, *i.e.* enhancing or detecting edges in the image. Filtering is a neighborhood operation, *in* which the value of any given pixel in the output image is determined by applying some algorithm to the values of the pixels in the neighborhood of the corresponding input pixel. The median filter is a sliding-window spatial filter. It replaces the value of the center pixel with the median of the intensity values in the neighborhood of that pixel. A median filter is more effective than convolution when the goal is to simultaneously reduce noise and preserve edges.

Pectoral muscle removal operation is important in medio-lateral oblique view (MLO), where the pectoral muscle, slightly brighter compared to the rest of the breast tissue, can appear in the mammogram. In properly imaged MLO mammograms, the pectoral muscle is visible as a triangular region of high-density at the upper posterior part of the image. Texture of the pectoral muscle may also be similar to some abnormalities and may cause false positives in the detection of suspicious masses. Pectoral muscles are the regions in mammograms that contain brightest pixels. These regions must be removed before detecting the tumor cells so that mass detection can be done efficiently.

### 3.2 Segmentation

Segmentation is the process of partitioning a digital image into multiple regions. For this purpose the entropy segmentation is used to segment the image. The following diagram shows the flow of entropy segmentation.



**Figure 1:** Segmentation algorithm



The simplest property that pixels in a region can share is intensity. So, a natural way to segment such regions is through thresholding, the separation of light and dark regions. Thresholding creates binary images from grey-level ones by turning all pixels below some threshold to zero and all pixels above that threshold to one.

Thresholding method in image segmentation that yields all the pixels and assumes the algorithm in two cases i.e. darkness and brightness.

### 3.3 Feature Extraction

After the segmentation part, the features are extracted from the segmented images which are used for the classification. Then by extracting the feature from segmented image the classifier gives output normal or abnormal image. There are various features like mean, standard deviation, Entropy, Skewness, Kurtosis, Variance, Energy, Correlation, Smoothness, and Root Mean Square. These features are calculated by following formulas: There are various features like mean, standard deviation, Entropy, Skewness, Kurtosis, Variance, Energy, Correlation, Smoothness and Root mean square (rms). These features are calculated by following formulas:

#### Mean-

The mean,  $\mu$  of the pixel values in the defined window, estimates the value in the image in which central clustering occurs. The mean can be calculated using the formula:

Histograms show the distribution of data values across a data range. They do this by dividing the data range into a certain

number of intervals, tabulating the number of values that fall into each interval and plotting the values in the bins using bars or wedges of varying height. Entropy is a concept of information theory. It is used to measure the amount of information. It is defined in terms of the probabilistic behavior of a source of information. Entropy can best represent the information containing in the image. The approach of image segmentation based on entropy algorithm is used to segment foreground and background image. Suppose  $p = \{p_1, p_2, \dots, p_n\}$  be

(3)

number of intervals, tabulating the number of values that fall into each interval and plotting the values in the bins using bars or wedges of varying height. Entropy is a concept of information theory. It is used to measure the amount of



in- formation. It is defined in terms of the probabilistic behavior of a source of information. Entropy can best represent the information containing in the image. The approach of image segmentation based on entropy algorithm is used to segment foreground and background image. Suppose  $p=\{p_1, p_2, \dots, p_n\}$   $b_p(i, j)$  is the pixel value at point  $(i, j)$  of an image of size  $M \times N$ .

### Standard deviation-

The Standard Deviation,  $\sigma$  is the estimate of the mean square deviation of grey pixel value  $p(i, j)$  from its mean value  $m$ . Standard deviation describes the dispersion within a local region

a finite discrete probability distribution that satisfies these conditions

$$p(t) \geq 0, \text{ where } t=0, 1, 2, \dots, n$$

(4)

The amount of uncertainty of the distribution, is called the entropy of the distribution,  $P$ . The Shannon entropy of the distribution,  $P$ , a measure of uncertainty and denoted by  $E(P)$

$$h = -\sum P r_k (\log P r_k)$$

Segmentation involves separating an image into regions (or their contours) corresponding to objects[1]. Usually try to segment regions by identifying common properties. Or, similarly, we identify contours by identifying difference between regions (edges). with the  $k^{\text{th}}$  grey level and  $L$  is the total number of grey levels.

### Skewness-

Skewness,  $S$  characterizes the degree of asymmetry of a pixel distribution in the specified window around its mean. Skewness is a pure number that characterizes only the shape of the distribution. The formula for finding Skewness is given in the below equation:

$$p(x_1, \dots, x_n) = \prod P(x_i - c_j)$$

The aim of supervised classification is to classify instances  $i$  given by certain characteristics  $x_i = \{x_{i1}, \dots, x_{in}\}$  into  $r$  class

Kurtosis,  $K$  measures the Peakness or flatness of a distribution relative to a normal distribution. The conventional definition of kurtosis is: labels,  $c_i$ ,  $i=1, \dots, r$ .  $x_{il}$  denotes the value of variable  $x_l$  observed in instance  $i$ . The main principle of a Bayesian classifier is the application of Bayes' theorem.





In this section, the results of the proposed approach are pre-

Variance is the square root of standard deviation or it is the average of the squared differences from the Mean.

### **Energy-**

Energy returns the sum of squared elements in the Grey Level Co-Occurrence Matrix (GLCM). Energy is also known as uniformity. The range of energy is [0 1].

Mathematical equation,

sented. First the preprocessing is done by the median filter and also pectoral muscles are removed. Then this image is segmented by using the entropy segmentation method, features are extracted from segmented image and the output result is shown with the help of Bayesian network. The Bayesian network shows the image is abnormal image.

### **Correlation-**

(9)

Correlation returns a measure of how correlated a pixel is to its neighbor over the whole image. The range of correlation is [-1 1]. Correlation is 1 or -1 for a perfectly positively or negatively correlated image. Correlation is NaN (Not a Number) for a constant image. The below equation shows the calculation of Correlation. Evaluates how a pixel is related to its neighbor.

(12)

Bayesian networks are a statistical method for Data Mining, a statistical method for discovering valid, novel and potentially useful patterns in data. Bayesian networks are used to represent essential information in databases in a network structure. The network consists of edges and vertices, where the vertices are events and the edges relations between events. The networks can be used to represent domain knowledge, and it is possible to control inference[11]. A simple usage of Bayesian networks is denoted naive Bayesian classification.

## **4. Conclusion**

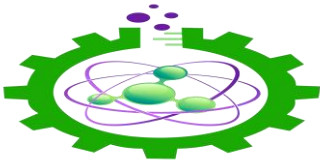
Although In this study, an automatic diagnosis system to detect the breast cancer by using Bayesian neural network is presented. In this study by using several preprocessing techniques the unwanted part is removed in the image. Using Entropy segmentation it shows the tumor area in the image. Then the Bayesian



classifier is used to show the image result on the basis of features that are extracted from the image. The accuracy of this method is high upto certain extent for the MIAS database. The results of this method can be improved by taking the combination of Bayesian network with another classifier.

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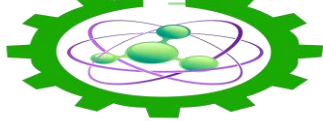
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[12] In the International Journal of Advanced Research in Computer and Communication Engineering, S. Kharya<sup>1</sup>, S. Agrawal<sup>2</sup>, and S. Soni published an article titled "Using Bayesian Belief Networks for Prognosis & Diagnosis of Breast Cancer" in February 2014, pages 5423–5427, Volume 3, Issue 2.

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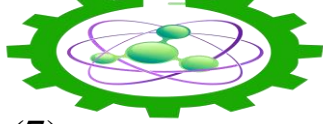


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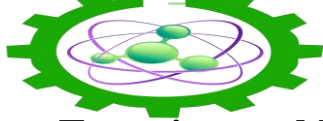
**ISSN: 1934--9955 [www.ijise.net](http://www.ijise.net)**

**Vol-09 Issue-01 May 2014**

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